

## Lecture 2: Symplectic reduction

In this lecture we discuss group actions on symplectic manifolds and symplectic reduction. We start with some generalities about group actions on manifolds.

### 2.1 Differentiable group actions

Let  $G$  be a connected Lie group and  $\mathfrak{g}$  its Lie algebra. Suppose  $G$  acts smoothly on a differentiable manifold  $M$ . Letting  $\mathcal{X}(M)$  denote the vector fields on  $M$ , we have a map

$$\begin{aligned} \mathfrak{g} &\rightarrow \mathcal{X}(M) \\ X &\mapsto \xi_X \end{aligned}$$

associating to each  $X \in \mathfrak{g}$  a vector field  $\xi_X$  on  $M$ . This map is a Lie algebra homomorphism:  $\xi_{[X,Y]} = [\xi_X, \xi_Y]$ , where in the RHS we have the Lie bracket of vector fields. On a function  $f \in C^\infty(M)$ ,

$$\xi_X f(m) = \left. \frac{d}{dt} f(e^{-tX} \cdot m) \right|_{t=0} .$$

This is an example of the Lie derivative. If  $\eta \in \mathcal{X}(M)$ , then  $\mathfrak{g}$  acts on it via

$$X \cdot \eta = [\xi_X, \eta] .$$

Similarly, if  $\theta \in \Omega^1(M)$  is a one-form, then for all  $\eta \in \mathcal{X}(M)$ ,

$$\begin{aligned} (X \cdot \theta)(\eta) &:= X \cdot \theta(\eta) - \theta(X \cdot \eta) \\ &= \xi_X \theta(\eta) - \theta([\xi_X, \eta]) . \end{aligned}$$

In general if  $\omega \in \Omega^p(M)$  is a  $p$ -form,

$$X \cdot \omega := (d\iota(\xi_X) + \iota(\xi_X)d)\omega ,$$

where  $d$  is the exterior derivative and  $\iota$  is the contraction operator defined by

$$(\iota(\xi)\omega)(\eta_1, \dots, \eta_{p-1}) = \omega(\xi, \eta_1, \dots, \eta_{p-1}) .$$

As a check of this formula, notice it agrees on functions and on one-forms.

Let  $\xi$  be a vector field and let  $\mathcal{L}_\xi$  denote the Lie derivative on differential forms:  $\mathcal{L}_\xi = d\iota(\xi) + \iota(\xi)d$ . Then the following identities are easy to prove:

- $\iota(\xi)\iota(\eta) = -\iota(\eta)\iota(\xi)$ ,
- $\mathcal{L}_\xi \iota(\eta) - \iota(\eta)\mathcal{L}_\xi = \iota([\xi, \eta])$ , and
- $\mathcal{L}_\xi \mathcal{L}_\eta - \mathcal{L}_\eta \mathcal{L}_\xi = \mathcal{L}_{[\xi, \eta]}$ ,

for all vector fields  $\eta, \xi$ .

## 2.2 Symplectic group actions

Now let  $(M, \omega)$  be a symplectic manifold. That is,  $\omega \in \Omega^2(M)$  is a closed non-degenerate 2-form. In other words,  $d\omega = 0$  and the natural map

$$\begin{aligned} \flat : \mathcal{X}(M) &\rightarrow \Omega^1(M) \\ \xi &\mapsto \xi^\flat = \iota(\xi)\omega, \end{aligned}$$

is an isomorphism with inverse  $\sharp : \Omega^1(M) \rightarrow \mathcal{X}(M)$ . In local coordinates,

$$\omega = \frac{1}{2} \omega_{ij} dx^i \wedge dx^j,$$

nondegeneracy means that  $\det[\omega_{ij}] \neq 0$ .

We now take a connected Lie group  $G$  acting on  $M$  via **symplectomorphisms**, i.e., diffeomorphisms which preserve  $\omega$ . Infinitesimally, this means that if  $X \in \mathfrak{g}$  then

$$\begin{aligned} 0 &= X \cdot \omega \\ &= d\iota(\xi_X)\omega + \iota(\xi_X)d\omega \\ &= d\iota(\xi_X)\omega, \end{aligned}$$

whence the one-form  $\iota(\xi_X)\omega$  is closed. A vector field  $\xi$  such that  $\iota(\xi)\omega$  is closed is said to be **symplectic**. Let  $\mathfrak{sym}(M)$  denote the space of symplectic vector fields. It is clear that the symplectic vector fields are the image of the closed forms under  $\sharp$ :

$$\mathfrak{sym}(M) = \sharp(\Omega_{\text{closed}}^1(M)).$$

If  $\xi^\flat$  is actually exact, we say that  $\xi$  is a **hamiltonian vector field**. This means that there exists  $\phi_\xi \in C^\infty(M)$  such that

$$\xi^\flat + d\phi_\xi = 0.$$

This function is not unique because we can add to it a locally-constant function and still satisfy the above equation. We let  $\mathfrak{ham}(M)$  denote the space of hamiltonian vector fields. Then we have that

$$\mathfrak{ham}(M) = \sharp(\Omega_{\text{exact}}^1(M)).$$

We can summarise the preceding discussion with the following sequence of maps

$$0 \longrightarrow H_{\text{dR}}^0(M) \xrightarrow{i} C^\infty(M) \xrightarrow{\sharp \circ d} \mathfrak{sym}(M) \xrightarrow{\flat} H_{\text{dR}}^1(M) \longrightarrow 0,$$

where the kernel of each map is precisely the image of the preceding. Such sequences are called **exact**.

A  $G$ -action on  $M$  is said to be **hamiltonian** if to every  $X \in \mathfrak{g}$  we can assign a function  $\phi_X$  on  $M$  such that  $\xi_X^\flat + d\phi_X = 0$ . In this case we have a map  $\mathfrak{g} \rightarrow C^\infty(M)$ .

In a symplectic manifold, the functions define a **Poisson algebra**: if  $f, g \in C^\infty(M)$  we define their **Poisson bracket** by

$$\{f, g\} = \omega(\xi_f, \xi_g),$$

where  $\xi_f$  is the hamiltonian vector field such that  $\xi_f^\flat + df = 0$ . The Poisson bracket is clearly skew-symmetric and obeys the Jacobi identity (since  $d\omega = 0$ ) and moreover obeys

$$\{f, gh\} = \{f, g\}h + g\{f, h\}.$$

In particular it gives  $C^\infty(M)$  the structure of a Lie algebra. A hamiltonian action is said to be **Poisson** if there is a Lie algebra homomorphism  $\mathfrak{g} \rightarrow C^\infty(M)$  sending  $X$  to  $\phi_X$  in such a way that  $\xi_X^\flat + d\phi_X = 0$  and that

$$\phi_{[X, Y]} = \{\phi_X, \phi_Y\}.$$

The obstruction for a symplectic group action to be Poisson can be measured cohomologically. Indeed, it is a mixture of the de Rham cohomology of  $M$  and the Chevalley–Eilenberg cohomology of  $\mathfrak{g}$ . For example, it is not hard to see that if  $\mathfrak{g}$  is semisimple then there is no obstruction. In fact, the obstruction can be more succinctly expressed in terms of the **equivariant** cohomology of  $M$ .

### 2.3 Symplectic reduction

If the  $G$ -action on  $M$  is Poisson we can define the **moment(um) map(ping)**

$$\Phi : M \rightarrow \mathfrak{g}^*$$

by  $\Phi(m)(X) = \phi_X(m)$  for every  $X \in \mathfrak{g}$  and  $m \in M$ . In a sense, this map is dual to the map  $\mathfrak{g} \rightarrow C^\infty(M)$  coming from the Poisson action. The group  $G$  acts both on  $M$  and on  $\mathfrak{g}^*$  via the coadjoint representation and the momentum mapping  $\Phi$  is  $G$ -equivariant, intertwining between the two actions. Indeed, since the group is connected, it suffices to prove equivariance under the action of the Lie algebra, but this is simply the fact that

$$\xi_X \phi_Y = \{\phi_X, \phi_Y\} = \phi_{[X, Y]}.$$

The equivariance of the moment map means that the  $G$ -action preserves the level set

$$M_0 := \{m \in M \mid \Phi(m) = 0\},$$

which is a closed embedded submanifold of  $M$  provided that  $0 \in \mathfrak{g}^*$  is a regular value of  $\Phi$ . In this case, we can take the quotient  $M_0/G$ , which, if the  $G$ -action is free and proper, will be a smooth manifold. In general, it may only be an orbifold. The following theorem is a centerpiece of this whole subject.

**Theorem 2.1** (Marsden–Weinstein). *Let  $(M, \omega)$  be a symplectic manifold and let  $G$  be a connected Lie group acting on  $M$  with an equivariant momentum mapping  $\Phi : M \rightarrow \mathfrak{g}^*$ . Let  $M_0 = \Phi^{-1}(0)$  and let  $\tilde{M} := M_0/G$ . If  $\tilde{M}$  is a manifold, then it is symplectic and the symplectic form is uniquely defined as follows. Let  $i : M_0 \rightarrow M$  and  $\pi : M_0 \rightarrow \tilde{M}$  the natural maps:  $i$  is the inclusion and  $\pi$  sends every point in  $M_0$  to the orbit it lies in. Then there exists a unique symplectic form  $\tilde{\omega} \in \Omega^2(\tilde{M})$  such that  $i^*\omega = \pi^*\tilde{\omega}$ .*

A common notation for  $\tilde{M}$  is  $M//G$ .

We will actually sketch the proof of a more general result, but before doing so we need to introduce some notation.

## 2.4 Coisotropic reduction

A symplectic vector space  $(V, \omega)$  is a vector space  $V$  together with a nondegenerate skew-symmetric bilinear form  $\omega$ . Nondegeneracy means that the linear map  $b : V \rightarrow V^*$  defined by  $v \mapsto \omega(v, -)$  is an isomorphism. The tangent space  $T_p M$  at any point  $p$  in a symplectic manifold is a symplectic vector space relative to the restriction to  $p$  of the symplectic form.

If  $W \subset V$  is a linear subspace of a symplectic vector space, we let

$$W^\perp := \{v \in V \mid \omega(v, w) = 0 \quad \forall w \in W\}$$

denote the **symplectic perpendicular**. Unlike the case of a positive-definite inner product,  $W$  and  $W^\perp$  need not be disjoint. Nevertheless, one can show that  $\dim W^\perp = \dim V - \dim W$ . A subspace  $W \subset V$  is said to be

- **isotropic**, if  $W \subset W^\perp$ ;
- **coisotropic**, if  $W^\perp \subset W$ ;
- **lagrangian**, if  $W^\perp = W$ ; and
- **symplectic**, if  $W^\perp \cap W = \{0\}$ .

It is easy to see that if  $W \subset V$  is isotropic, then  $\dim W \leq \frac{1}{2} \dim V$ , whereas if it is coisotropic, then  $\dim W \geq \frac{1}{2} \dim V$ . Lagrangian subspaces are both isotropic and coisotropic, whence they are middle-dimensional. Notice that the restriction of the symplectic structure to an isotropic subspace is identically zero, whereas if  $W$  is coisotropic, the quotient  $W/W^\perp$  inherits a symplectic structure from that of  $V$ .

Now let  $(M, \omega)$  be a symplectic manifold and let  $N \subset M$  be a (closed, embedded) submanifold. We say that  $N$  is **isotropic** (resp. **coisotropic**, **lagrangian**, **symplectic**) if for every  $p \in N$ ,  $T_p N \subset T_p M$  is isotropic (resp. coisotropic, lagrangian, symplectic).

If  $G$  acts on  $(M, \omega)$  giving rise to an equivariant moment mapping  $\Phi : M \rightarrow \mathfrak{g}^*$ , then the zero locus  $M_0$  of the moment mapping turns out to be a coisotropic submanifold. To prove this we need to show that  $(T_p M_0)^\perp \subset T_p M_0$  for all  $p \in M_0$ . This will follow from the following observation. A vector  $v \in T_p M$ ,  $p \in M_0$ , is tangent to  $M_0$  if and only if  $d\Phi(v) = 0$ . However, for all  $X \in \mathfrak{g}$ ,

$$d\Phi(v)(X) = d\phi_X(v) = \omega(v, \xi_X),$$

which shows that  $(T_p M_0)^\perp$  is the subspace of  $T_p M$  spanned by the  $\xi_X(p)$ ; in other words, the tangent space of the  $G$ -orbit  $\mathcal{O}$  through  $p$ . Now  $G$  preserves  $M_0$ , whence  $\mathcal{O} \subset M_0$  and hence  $(T_p M_0)^\perp = T_p \mathcal{O} \subset T_p M_0$ .

We will now leave the case of a  $G$ -action and consider a general coisotropic submanifold  $M_0 \subset M$  and let  $i : M_0 \rightarrow M$  denote the inclusion. Let  $\omega_0 = i^* \omega$  denote the pull-back of the symplectic form to  $M_0$ . It is not a symplectic form, because it is degenerate. Indeed, its kernel at  $p$  is  $(T_p M_0)^\perp \subset T_p M_0$ . We will assume that  $\dim(T_p M_0)^\perp$  does not change as we move  $p$ . In this case, the subspaces  $(T_p M_0)^\perp \subset T_p M_0$  define a distribution (in the sense of Frobenius) called the **characteristic distribution** of  $\omega_0$  and denoted  $TM_0^\perp$ . We claim that it is integrable.

Let  $v, w$  be local sections of  $TM_0^\perp$ , we want to show that so is their Lie bracket  $[v, w]$ . This follows from the fact that  $\omega_0$  is closed. Indeed, if  $u$  is any vector field tangent to  $M_0$ , then

$$\begin{aligned} 0 &= d\omega_0(u, v, w) \\ &= u\omega_0(v, w) - v\omega_0(u, w) + w\omega_0(u, v) \\ &\quad - \omega_0([u, v], w) + \omega_0([u, w], v) - \omega_0([v, w], u). \end{aligned}$$

All terms but the last vanish because of the fact that  $v, w \in TM_0^\perp$ , leaving

$$\omega_0([v, w], u) = 0 \quad \text{for all } u \in TM_0,$$

whence  $[v, w] \in TM_0^\perp$ .

By the Frobenius integrability theorem,  $M_0$  is foliated by connected submanifolds whose tangent spaces make up  $TM_0^\perp$ . Let  $\tilde{M}$  denote the space of leaves of this foliation and let  $\pi : M_0 \rightarrow \tilde{M}$  denote the natural surjection taking a point of  $M_0$  to the unique leaf containing it. Then locally (and also globally if the foliation ‘fibers’)  $\tilde{M}$  is a manifold whose tangent space at a leaf is isomorphic to  $T_p M_0 / T_p M_0^\perp$  for any point  $p$  lying in that leaf. We then give  $\tilde{M}$  a symplectic structure  $\tilde{\omega}$  by demanding that  $\pi^* \tilde{\omega} = \omega_0$ . In other words, if  $\tilde{v}, \tilde{w}$  are vectors tangent to a leaf, we define  $\tilde{\omega}(\tilde{v}, \tilde{w})$  by choosing a point  $p$  in the leaf and lifting  $\tilde{v}, \tilde{w}$  to vectors  $v, w \in T_p M_0$  and declaring  $\tilde{\omega}(\tilde{v}, \tilde{w}) = \omega_0(v, w)$ . We have to show that this is well-defined, so that it does not depend neither on the choice of  $p$  nor on the choice of lifts. That it does not depend on the choice of lifts is

basically the algebraic result that since  $T_p M_0 \subset T_p M$  is a coisotropic subspace,  $T_p M_0 / (T_p M_0)^\perp$  inherits a symplectic structure. To show independence on the point it is enough, since the leaves are connected, to show that  $\omega_0$  is invariant under the flow of vector fields in  $TM_0^\perp$ . So let  $v \in TM_0^\perp$  and consider

$$\mathcal{L}_v \omega_0 = d\iota(v)\omega_0 + \iota(v)d\omega_0,$$

which vanishes because  $\omega_0$  is closed and  $\iota(v)\omega_0 = 0$ .

Finally, we show that  $(\tilde{M}, \tilde{\omega})$  is symplectic by showing that  $\tilde{\omega}$  is smooth and closed. Smoothness follows from the fact that  $\pi^* \tilde{\omega}$  is smooth. To show that it is closed, we simply notice that

$$\pi^* d\tilde{\omega} = d\pi^* \tilde{\omega} = d\omega_0 = 0,$$

and then that  $\pi_*$  is surjective.

In summary we have proved<sup>1</sup> the following:

**Theorem 2.2.** *Let  $(M, \omega)$  be a symplectic manifold and  $i : M_0 \hookrightarrow M$  be a coisotropic submanifold. Then the space of leaves  $\tilde{M}$  of the characteristic foliation of  $i^* \omega$  inherits locally (and globally, if the foliation fibers) a unique symplectic form  $\tilde{\omega}$  such that  $\pi^* \tilde{\omega} = i^* \omega$ , where  $\pi : M_0 \rightarrow \tilde{M}$  is the natural surjection.*

Notice that the passage from  $M$  to  $\tilde{M}$  is a subquotient: one passes to the coisotropic submanifold  $M_0$  and then to a quotient. This is to be compared with the cohomology of a complex which is also a subquotient: one passes to a subspace (the cocycles) and then projects out the coboundaries. It therefore would seem possible (or even plausible) that there is a cohomology theory underlying symplectic reduction. Happily there is and is the topic to which we now turn.

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<sup>1</sup>modulo the bit about  $TM_0^\perp$  having constant rank, but we only used this in order to use Frobenius's Theorem. There is another integrability theorem due to Sussmann, which does not require that  $TM_0^\perp$  have constant rank.